Analysis of ignition risk on mechanical equipment in ATEX
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To cite this version:

HAL Id: ineris-00973260
https://hal-ineris.archives-ouvertes.fr/ineris-00973260
Submitted on 4 Apr 2014

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Abstract - Until the implementation of the ATEX directive 94/9/CE, the certification of equipment intended to explosive atmospheres was only dedicated to electrical equipment. Since the 1st July 2003, the non-electrical sources of inflammation are also to be looked at before putting an ATEX equipment on the market (pumps, couplers, reducing gears, ...).

Among these sources, mechanical friction and impacts are a main cause of ignition of explosive atmosphere. The risk analysis of the equipment consists in considering the failures, which can lead to ignition. If the failure involves a friction between two parts or an impact, we shall estimate if this friction or impact dissipates a sufficient amount of energy to ignite the surrounding explosive atmosphere.

As part of the European program MECHEX, we have studied the process of degradation of the mechanical energy into heat during friction and impacts and we have examined the mechanisms of ignition at the contact zone.

An extensive experimental program is presented and some "simple" modelling is proposed on purpose of practical applications. For frictional situations, a critical rubbing power is calculated without any limitations as for a potential lower boundary concerning the rubbing velocity. For "impacts", the relevant parameter for ignition is not the kinetic energy of the projectile but its velocity and the nature of the materials.

Index Terms — ATEX, Mechanical ignition source, Non-electrical Equipment

I. INTRODUCTION

Since the implementation of the ATEX directive 94/9/CE [1] in July 2003, the non-electrical sources of inflammation shall also be examined before putting an ATEX equipment on the market (pumps, couplers, reducing gears, ...).

European harmonized standards have been developed by CEN/TC 305 WG2 to give requirements for non-electrical equipment. The basic standard for non-electrical equipment is the EN 13463-1 [2], which requires an ignition hazard assessment of the equipment.

Concerning mechanical equipment, this assessment often underlines the possibility of mechanical friction or impacts as an ignition source during foreseeable or rare malfunction. When such a source appears, the manufacturer shall estimate if the friction or impact dissipates a sufficient amount of energy to ignite the surrounding explosive atmosphere.

The European program MECHEX was dedicated to the study of the process of ignition during friction and impact.
or establishment for the first time before 30 June 2003 shall comply from that date with the minimum requirements laid down in Annex II, Part A. So all necessary measures must be taken to ensure that the work equipment have been designed, constructed, assembled and installed, and are maintained and operated, in such a way as to minimize the risks of an explosion.

To comply with the requirements of the Directive 94/9/CE we may generally use the harmonized standard EN13463-1. We can also use the frame of this standard to carry the hazard assessment of the equipment that is already installed and to include this assessment to the explosion protection document demanded by the directive 1999/92/CE.

The standard EN 13463-1 is based on the assessment of the ignition hazards of equipment depending on the category of this equipment. It can be used as a stand-alone standard but for mechanical equipment the standard EN 13463-5 [4] is generally used in addition. This standard defines the protection concept “constructional safety” with marking “c”. The principle of this type of protection is to apply constructional measures so as to protect against the possibility of ignition from hot surfaces, sparks and adiabatic compression generated by moving parts. The requirements are based on good engineering principles, so that risk of mechanical failures likely to create incendive temperatures or sparks, are reduced to a very low level.

B. Ignition Hazard Assessment

The ignition hazard assessment consists in reviewing all potential ignition sources of the equipment and in distinguishing normal operation, expected malfunction and rare malfunction. Then will be considered the measures applied to prevent each source becoming effective.

Concerning mechanical equipment with moving parts the hazard assessment will often underline the risk of friction or impact as an expected or rare malfunction. That could be the case for instance for pumps when there is no more fluid and where parts could enter in contact in rare malfunction. We can also think to the bearings or to the friction of a roller on a rail.

When the malfunction introducing a risk of friction or impact is identified, the problem is then to determine if this friction or impact could become an effective ignition source or not. The type of source could then be a hot surface or sparks but it is difficult to know if the phenomena are sufficient to ignite the explosive atmosphere.

III. MECHANICAL FRICTION AND IMPACT

A. IGNITION RISK BY FRICTION

Friction between two solid bodies is a process through which mechanical energy is transformed into heat. Experience reveals that heat is produced in the rubbing zone where the material is severely stretched and diffuses outwards. It is well known that the amount of heat evolved is in proportion of the applied force and sliding speed [6].

Further, if the friction is sufficiently intense, some material may be torn away resulting in fragments being expelled. This event is sometimes called “friction sparks” or “spark shower”.

**Experimental equipment**

For a given heat power produced in the rubbing zone [7], traditional thermodynamical laws tell that the maximum temperature may depend on some geometrical sizes (area of the contact zone, diameter of the machine, ...) of the rubbing equipment. Mainly for this reason, two experimental set-ups have been used (figure 1). The configuration of a fixed slider rubbing onto a rotating wheel has been selected because a rather precise control of the rubbing parameter is amenable.

The larger device [8] is a 30 cm diameter wheel, 22 mm thickness rubbing against a 40 mm high, 25 x 25 mm square cross section slider for most tests. The sliding velocity can be adjusted between 0.2 and 20 m/s and the normal load between 0 and 5000 N.

The smaller device is a 10 cm wheel, 8 mm thick rubbing against a 15 mm high, 7 x 7 mm square cross section slider. The sliding velocity can be adjusted between 0.05 and 15.7 m/s and the normal load between 0.2 and 1000 N.

Temperatures have been measured by optical methods and thermocouples. During the tests, the normal load, friction coefficient and speed were controlled [5, 8, 10].

![Figure 1: rubbing experimental set-ups (Large scale 30 cm dia. wheel - left and small scale 10 cm dia. wheel –right)](image)

The evolution of the rubbing temperature as function of the nominal power expressed in terms of normal load (N) times the sliding velocity (V) is shown on figure 2 for the various sliders used and the two machines. There is a clear trend of increasing the rubbing temperature as function of the nominal power. There is also a clear incidence of the nature and of the width of the slider and globally of the size of the rubbing machine.
local temperature is large enough according to the mechanism of the hot plate [9]. The experimental investigation and some theoretical evidence shows that the critical parameter is the temperature of the hot zone, of the order of hundreds of °C.

- The power dissipated in friction may easily be of the order hundreds of Watts. If the friction is occurring in a sufficiently confined area, the mean temperature of the ATEX may rise and reach the autoignition point. This situation should well be represented by the standard ignition temperatures;

- The sparks may be a cause of ignition. However, since the initial temperature at the beginning of the flight should not be different from that of the rubbing zone, the sparks are likely to constitute a preferential cause of ignition only if, later in their flight, their temperature increases well above that of the rubbing zone. This may occur if the flying particles are able to burn. In this case, the ignition process may be linked to the spark ignition mechanism referring to minimum ignition energies.

**Ignition around the heated surface**

This ignition mechanism is believed to be the main cause for mechanical ignition [8, 12] often invoked but, to our knowledge, never really proven.

For friction, experiments performed with the large scale rubbing machine used in explosive atmospheres and filmed with high speed video [8] demonstrate clearly that ignition proceeds at the rubbing zone. It occurs as soon as some critical temperature threshold has been reached at the rubbing zone. These temperatures have been estimated for a number of atmospheres (hydrogen-air, methane-air, propane-air, ethylene-air, diethyl-ether-air, acetone-air,…) and compared to critical temperatures determined previously [9] for hot surface ignition in explosive atmospheres ($T_{pcrit}$). It has been realized that both sets of values correlate extremely well demonstrating that “frictional” ignition is a “hot surface” ignition mechanism. It has been however noted that the critical hot surface temperature does not seem to correlate so well with the standard autoignition temperature nor better with the minimum ignition energy [5], indicating that this might be a new type of ignition criterion.

**Mechanisms of ignition**

The analysis reveals that ignition during friction and impacts may result from three different processes [7]:

- In direct contact with the hot rubbing zone whenever the

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**Figure 2**: Rubbing temperature as function of N.V for various sliders and the two machines (on the top, only with the small scale equipment, in the middle, only with the large scale equipment and on the bottom graph a comparison of the results with the two machines with a hard steel–mild steel rubbing configuration)

In some tests, flying fragments (sparks material) have been collected in order to evaluate the size of them and the wear rate. For steel rubbing against steel at a few m/s, the typical particle size seems of the order of a few hundred of mm and the wear rate, extremely dependent on the experimental conditions, is better scaled in mm$^3$/s [5].

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**Figure 3**: tabulated critical hot surface ignition temperature and observed contact temperature upon ignition during friction
Volumetric ignition

Experiments on the small scale rubbing machine with steel_steel configuration have shown only a moderate increase of the average temperature throughout a volume in closing the wheel (40°C) and inside the spark shower as compared to the temperature reached at the rubbing zone (700°C). So the ignition should occur most probably at the hot contact zone before any possibility of ignition throughout volume could arise [5].

Sparks

There was no evidence of any ignition to be undoubtedly attributable to a flying spark in the present experiments [5]. There was even no evidence of any fragment to burn in the surrounding atmosphere even in the extreme situation of aluminum rubbing intensively against hard steel. Is it to be said that only the situation of a light alloy rubbing against some rusty material and leading to “thermite reactions” [12] is to be considered for “spark” ignition during friction?

To help and clarify this important point, explosive atmospheres were submitted to a small chemically inert and artificially heated object, simulating a fragment [5]. Globally, the required temperature to produce ignition is well above the critical “hot surface” temperatures apart from the specific case of sulphur, which need to be further analysed. Thus, it is confirmed that the “spark” temperature need to be well above those of the rubbing zone to generate an increased risk of ignition suggesting that the fragments have to burn somehow.

Modelling

These findings have been analyzed and collapsed into a reasonable model [4]. It is postulated that ignition would occur at the hottest point, in the immediate vicinity of the rubbing zone (we thus leave apart the specific case of a thermite reaction). Following, the ignition parameter is the critical hot surface temperature defined before, depending on the nature of the atmosphere. We then have to derive the contact temperature reached at the rubbing zone (700°C). So the temperature in the rubbing zone depends only on the friction power calculated how much heat is produced in the friction. This amount of heat is driven out from the contact zone by thermal conduction and is modeled as a local heat source onto an semi-infinite solid [10]. The final equation reads:

\[
q = f \cdot N \cdot V = \frac{4}{\pi} \cdot (\lambda_1 + \lambda_2) \cdot \frac{A}{R} \cdot (T_f - T_{amb})
\]

where

- \( T_f \) : temperature of the rubbing zone
- \( T_{amb} \) : ambient temperature (boundary temperature of the bodies)
- \( R \) : radius of contact area
- \( A \) : contact area
- \( \lambda_i \) : heat conductivity of body i in the rubbing zone
- \( f \) : friction coefficient
- \( N \) : normal load

V : rubbing velocity

q : heat dissipated in friction

For the practical use of this expression within the frame of explosion safety, the following aspects need to be considered:

- a proper choice of the critical ignition temperature must be made. For explosive atmospheres, the relevant parameter would be \( T_{ign} \) which is above but not directly related to the standard ignition temperature;
- the area of the contact zone depends on the geometry of the device and may be found with a detailed analysis of the system. It should not be smaller than the ratio of the normal load to the Brinell Hardness which gives a lower boundary for \( R \);
- the critical power dissipated in rubbing (\( q = f \cdot N \cdot V \)) is the part lost in the friction which, in normal operation, is usually a very low fraction of the nominal power, typically a few percent for friction coefficients of the order of 0.001 to 0.01. Only in case of severe malfunction (a shaft broken, a fused bearing…), the friction power may reach the nominal power with a friction coefficient between 0.1 and 1..

Some comparison between this simplified method and experimental data is shown on figure 4. Here, the rubbing situation typically corresponds to a severe malfunction as defined above with a friction coefficient equated to unity. The model gives a lower estimate of the critical power but is reasonable in trends and order of magnitude.

Figure 4 : performances of the simplified model for frictional ignition against existing data [7] and results issued from the present program

This physical analysis implies that the maximum temperature in the rubbing zone depends only on the friction power without any limitations about any lower boundary about the rubbing velocity. For instance, it has been possible to ignite propane-air, ethylene-air and hydrogen-air mixtures at rubbing velocities equal to or even smaller than 1 m/s, which has been sometimes given a “safe” limit [10].

\[
\begin{align*}
\text{Figure 4: performances of the simplified model for frictional ignition against existing data [7] and results issued from the present program.}
\end{align*}
\]
B. IGNITION RISK BY IMPACT

**Experimental equipment**

The experimental facility consists of a free fall vertical device. The target is a strong mild steel plate (5 mm x 70 cm x 45 cm) anchored on a rigid thick wood plate (11 cm) impeding flexion during impact. The plate is inclined to favor a glancing blow. In most experiments the angle of 60° has been chosen. The projectile (diameter 18 mm of steel, aluminium, copper,...) is propelled by an air cannon on a precise point of the target at variable velocity between 5 to 50 m/s.

![Figure 5: Experimental impact test equipment](image)

The impact was filmed with a high speed camera in order to estimate the impact speed and to detect the fragments. Simultaneously, the temperature in the contact zone was measured with a high speed monochromatic pyrometer [5, 7].

A sample of those measurements is shown on figure 6. The impact results in a sharp temperature rise (up to hundreds of °C in a few tens of microseconds) followed from a rapid but more progressive decrease (in milliseconds). Usually a chip is produced which constitutes a unique fragment of mm size.

![Figure 6: typical temperature reading and excerpts from the high speed film (18 mm steel rod of 20 cm long, impacting at 10 m/s)](image)

Some data are shown on figure 7 for various experimental conditions. The impact temperature depends primarily upon the impact velocity and nature of the material and only very weakly on the size of the projectile. A further analysis of the same data shows that the impact temperature is not correlated to the incident kinetic energy [5].

![Figure 7: Maximum impact temperature of the hot spot for various conditions](image)

The physical analysis of the results [5, 7] suggests that the efforts, deformations, fragment production... should be the consequence of the strain waves produced in the very first moments of the impact and propagated at the speed of sound in the materials. These waves are responsible for the rebound. The experimental evidence suggests also that heat is produced due to some intense but very short rubbing on the target during the time of the rebound, while the projectile slides against the target with the tangential component of the impact velocity. The amount of heat produced is then driven away by transient thermal conduction A model has been proposed elsewhere [5] and the final equation reads:
\[ (T_{\text{imp}} - T_{\text{amb}}) = f \cdot K_m \cdot V^2 \cdot \sqrt{L} \]

where \( L \) stands for the length of the projectile and \( V \) the impact velocity. \( T_{\text{imp}} \) is the peak temperature reached during the impact. \( K_m \) is a composite parameter dependant only on the intrinsic properties of the bodies like sound speeds, specific masses and heat capacities, thermal conductivity \( K_m \) is typically of the order of 10 (20 for steel) in SI units.

About ignition, both the fragment, if any, and the hot spot may contribute to ignition equally because of their similar size. It has been found also [5], that the ignition process is closer to a hot spot mechanism as described before than to the standard spark ignition mechanism. Because of the short duration of the hot spot during an impact, the critical ignition temperature appears larger, by a factor between 1 to 2 depending on the atmosphere.

For the practical use of the preceding expression, a friction coefficient of 1 may be selected. \( \sqrt{L} \) may easily vary in more than a ratio of 10 whereas \( T_{\text{crit}} \) varies only in a ratio of 2. It is then tempting to use this formula by setting \( K_m \) to 20, a rather large value, and \( T_{\text{imp}} \) to 550°C, one of the smallest practical ignition temperature, \( L \) being the remaining unique variable equal to the largest dimension of the projectile. It is finally very simple to find an order of magnitude of a critical impact velocity, capable of igniting an explosive atmosphere. A comparison with data from the literature [7] is presented in figure 8.

The comparison is less favorable than for friction but impact ignition tests are difficult to perform because of a rather poor reproducibility. Nevertheless, this very simplified approach seems conservative apart from the specific situations of “thermite” reactions or large objects, mostly because, we believe, the exact geometry of the projectile is not precisely known.

As a final remark, the kinetic energy of the projectile does not appear, at any moment, neither in the data reduction of the experiments nor in the theoretical approach as Rasuo [11] noticed earlier. The velocity of the impact appears as a more convenient parameter.

**IV. PRACTICAL IMPLICATIONS**

The foregoing simplified models are issued from a more sophisticated tool in which the various equations are solved
A gasoline pump supplier is concerned by the explosion hazard raised by a new type of connector to feed LPG in cars. The possibilities of an impact of the connector on some solid surface and of a friction due to the rubbing along a moving vehicle were identified. Impact and rubbing experiments have been performed. Both the connector and the rubbing/impact surfaces are mainly made of steel. The typical diameter of the connector is 5 cm. Given the geometry of the connector, a typical rubbing size of 10 mm was chosen.

For LPG, the critical ignition hot spot temperature is about 650°C. At this level of temperature, the steel-steel friction coefficient is about 0.3.

The use of the foregoing simplified expressions reveals that the critical impact velocity would be of the order of 23 m/s and the critical rubbing power of about 800 W (N.V = 800/0.3=2500 W). Experiments have shown that the peak impact temperature is about 630°C at 28 m/s and the rubbing temperature is close to 300°C with a rubbing power of 400 W (N.V = 1200 W). Recalling that the rubbing temperature has been observed to be approximately proportional to N.V, the experimental observations seem coherent with the predictions.

On the practical side, those values seem high with regard to the normal way of operating the device and the considered risk might only appear in case of rare events.

V. CONCLUSION

Since the implementation of the ATEX directive 94/9/CE in July 2003, the non-electrical sources of inflammation shall also be examined before putting an ATEX equipment on the market (pumps, couplers, reducing gears, …). European harmonized standards have been developed by CEN/TC 305 WG2 to give requirements for non-electrical equipment. The basic standard for non-electrical equipment is the EN 13463-1, which requires an ignition hazard assessment of the equipment with the list of all potential ignition sources. Depending on the category of the equipment (1, 2 or 3), inducing the area where it can be installed (zone 0, 1, 3 or 20, 21, 22), the assessment has to be carried considering only normal use or also foreseeable or rare malfunction. The same work can be done to ensure that the equipment already in use fulfills the requirements of the directive 1999/92/CE and can be described in the explosion protection document.

Concerning mechanical equipment, this assessment often underline the possibility of mechanical friction or impacts as an ignition source during foreseeable or rare malfunction. When such a source appears, the manufacturer shall estimate if the friction or impact emits a sufficient energy to ignite the surrounding explosive atmosphere.

The European program MECHEX has permitted to study the process of ignition during friction and impact. The process of degradation of the mechanical energy into heat during friction or impacts and the mechanisms of ignition at the contact zone have been studied.

An extensive experimental program is presented in this paper but many points have only been surveyed. It was found that,
VII. REFERENCES


VIII. VITA

Dipl. Ing. Claire Petitfrere leads a certification team concerning equipment intended to explosive atmospheres in INERIS since 2002. She is a member of standardisation group WG2 from TC305 dealing with standards for non electrical equipment in explosive atmospheres.

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